

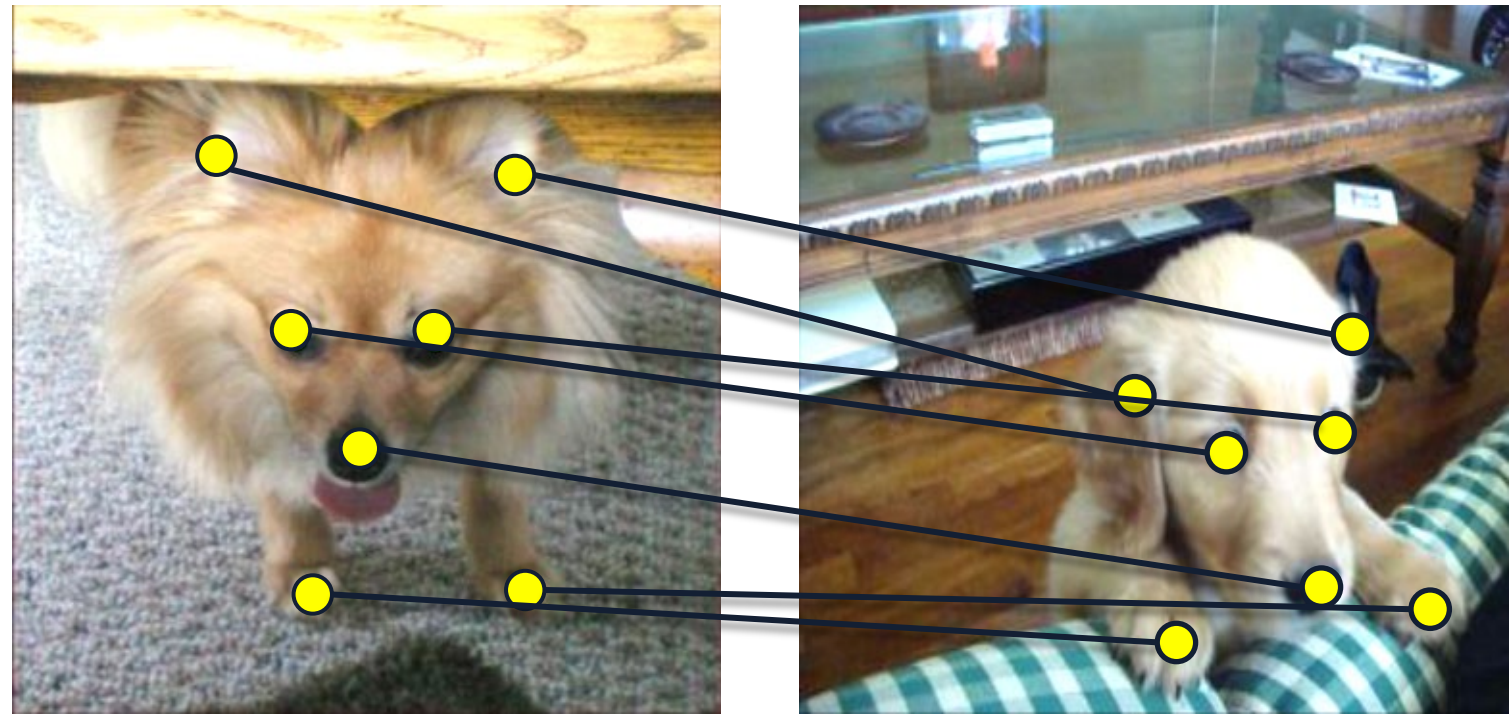
# PatchMatch-Based Neighborhood Consensus for Semantic Correspondence

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## INTRODUCTION

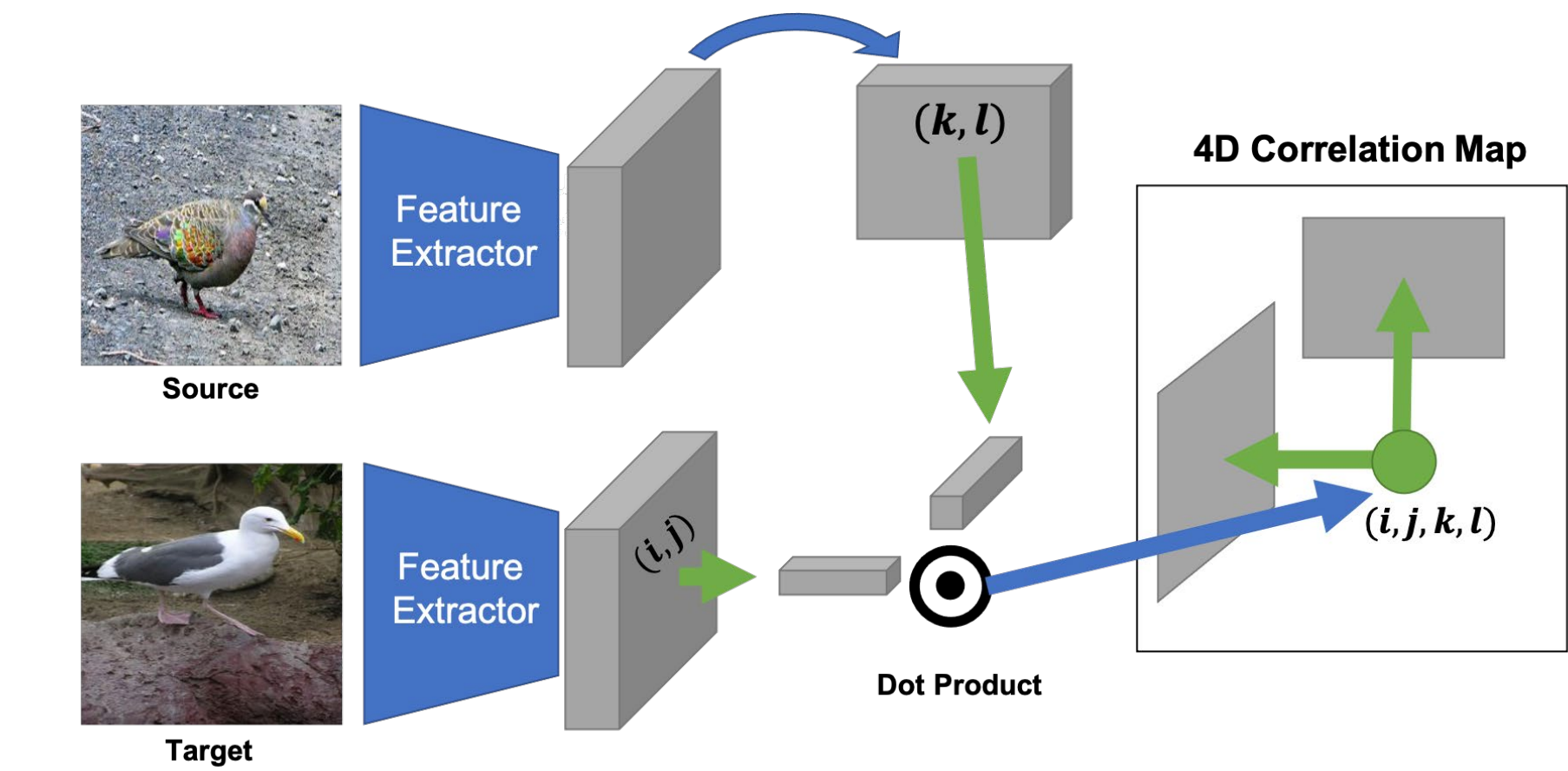
### Semantic Correspondence Problem



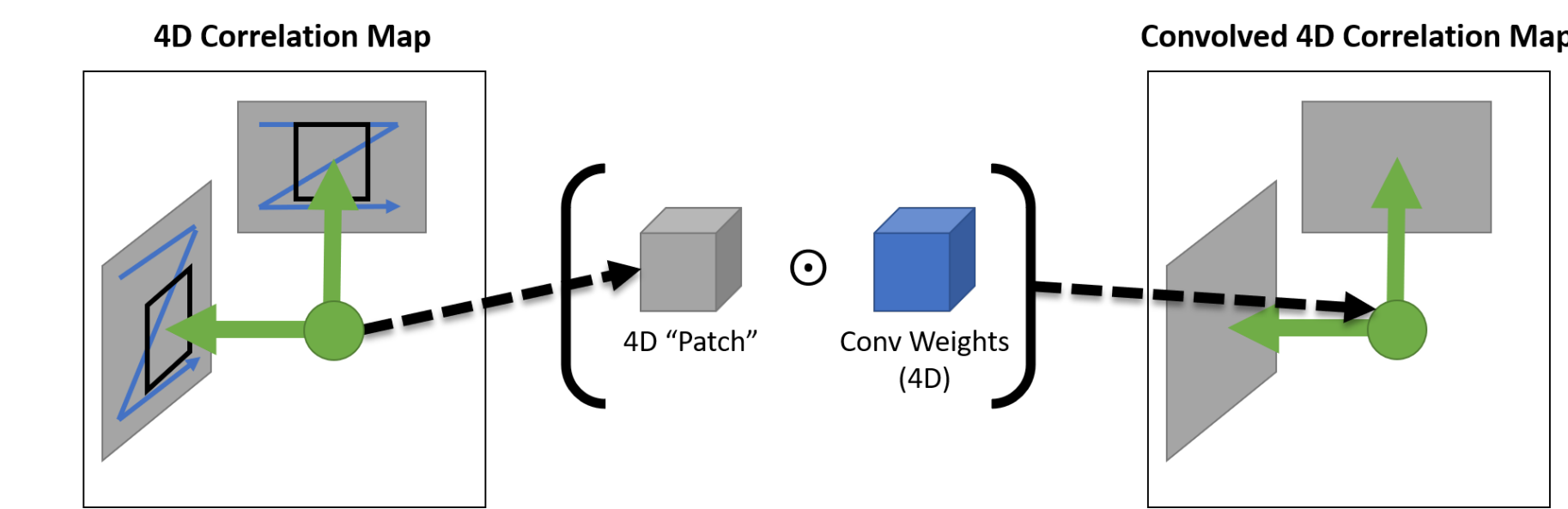
**Related works:** NC-Net (Rocco et al. 2018; NeurIPS), ANC-Net(Li et al. 2020; CVPR)

## REVIEW: NEIGHBORHOOD CONSENSUS

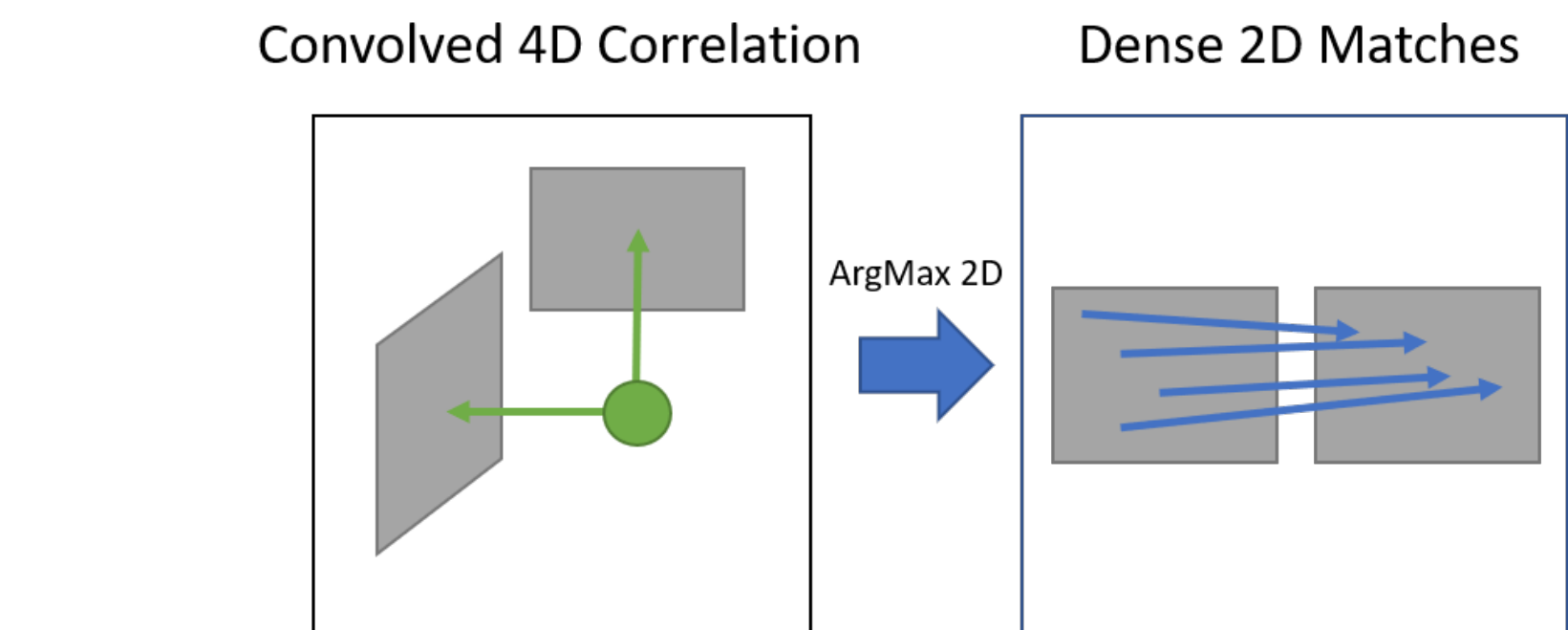
### 1. Computing 4D Correlation Maps



### 2. 4D Convolution over 4D Correlation Maps



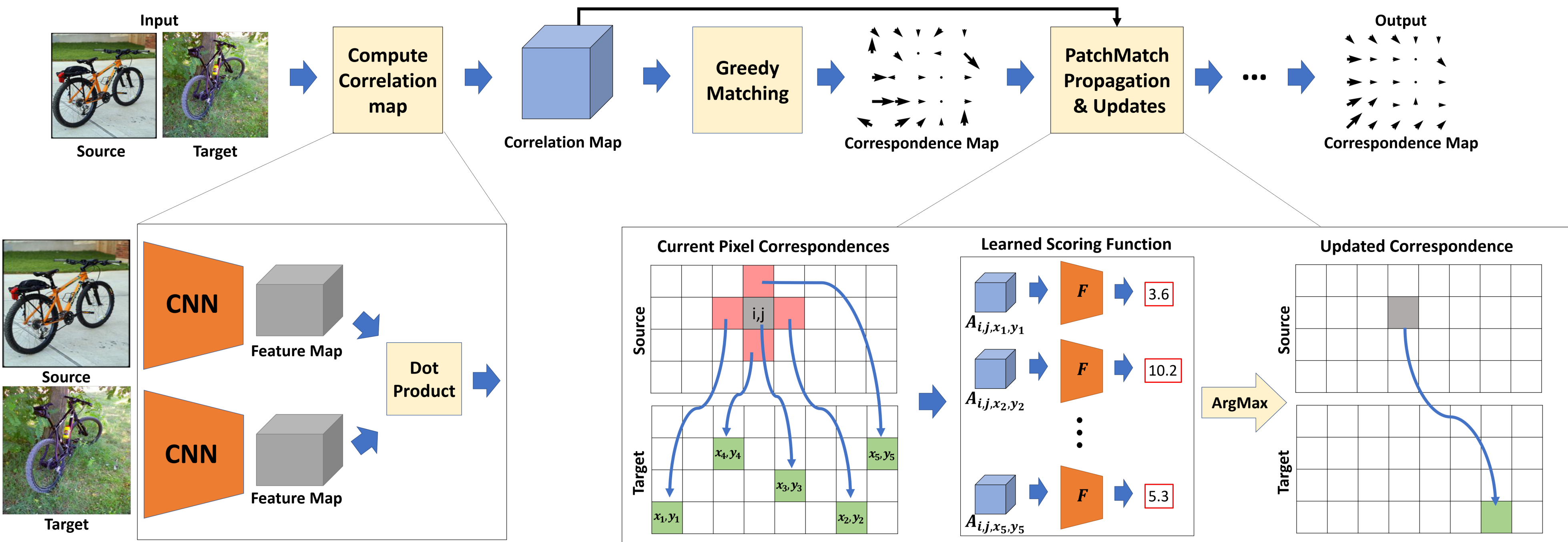
### 3. Find best Correlation Value at each pixel



## PATCHMATCH-BASED INFERENCE

### Accelerate Inference using PatchMatch

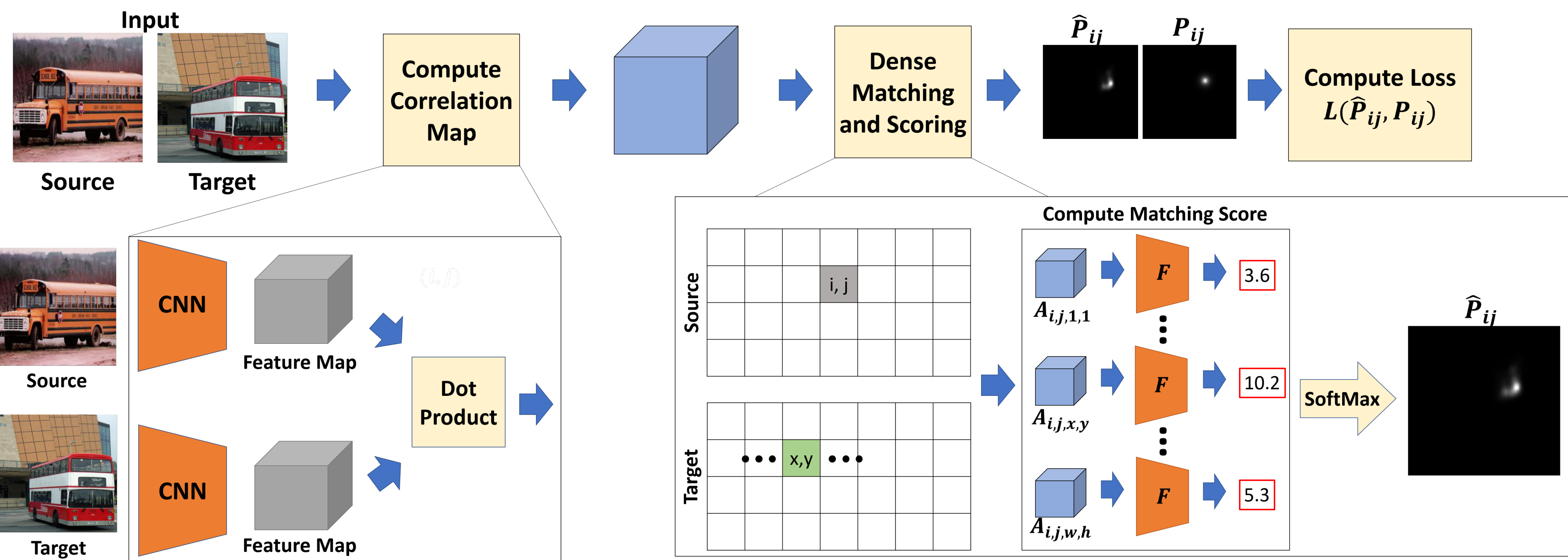
- Replace full 4D Convolution with PatchMatch
- Time Complexity:  $O(N^4)$  vs  $O(NMr^4)$  where  $N = \text{Max}(W, H)$ ,  $M = \text{PatchMatch iterations}$ ,  $r = \text{Patch size}$



## TRAINING 4D SCORING FUNCTION

### Proxy model for training 4D Neighborhood Consensus based scoring function

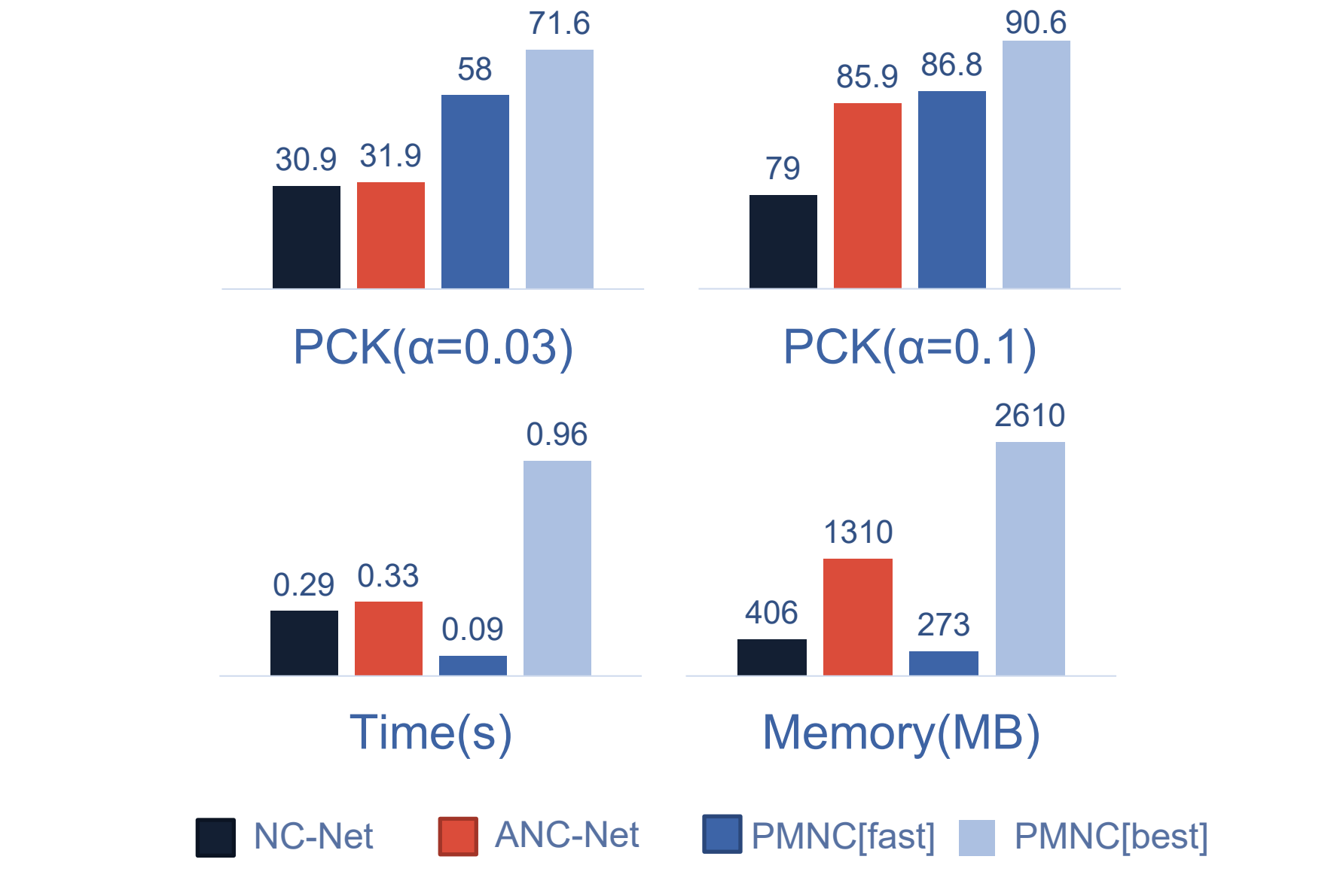
- For each annotation in the source image
- Computes 2D matching probability distribution of all pixels on the target image
- Loss given by cross entropy between expected and the ground truth annotation



## RESULTS

### PF-Pascal

- State of the art performance for all thresholds
- The fastest and uses the least memory



### SPair-71K

- State of the art performance (50.4%)
- Robust to different nuisances by a significant margin

### PCK per Nuisances

